Human Interaction in Industrial Tele-Operated Driving: Laboratory Investigation

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RISE Visual Media Quality Lab





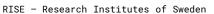
Background of remote-control industrial applications

Collaboration with Volvo CE to test 5G enabled on remote-controlled wheel loaders

https://www.pitandquarry.com/volvo-ce-to-test-5g-enabled-remote-controlled-wheel-loaders/

Collaboration with HIAB to test latency impacts on remote-controlled log lift forestry cranes





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Enabled Teleoperated driving in industries



How well users experience the quality of visual information delivery in ToP?



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On-going work: Collaboration with Volvo CE: Remote control of heavy machines

Investigating video manipulating impacts on drivers' performance

Plan developed for a field test

Study to be performed in early 2023 Postponed to after summer

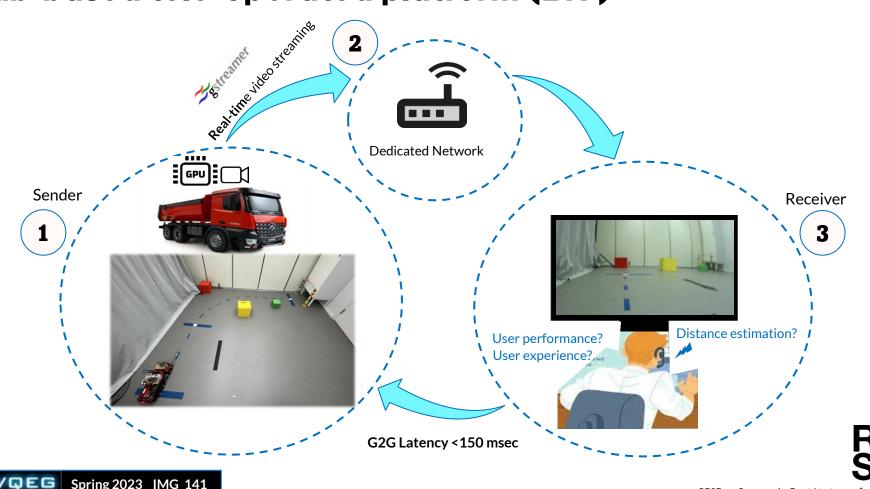
Study latency impacts







Lab-based tele-operated platform (LTP)



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Test set up

VQ: Video Quality levels	L: Video Latency	FoV: Field of view
(Frame rate 30 fps)		(Degrees)
Q1: 720 $r_w \times 640 r_h$	L1: 150 ms	F1: 120
Q2: 640 $r_w \times 480 r_h$	L2: 400 ms	F2: 105
Q3: 480 $r_w \times 320 r_h$	L3: 650 ms	-

RQ1) Impact of VQ and FoV on depth perception RQ2) Impact of VQ, FoV and L on Overall User experience RQ3) Impact of VQ, FoV and L on Use's performance

Participants: fourteen naive participants took part, four in the pilot, and ten in the main test (four female, ten male, mean age 29 + - 5).

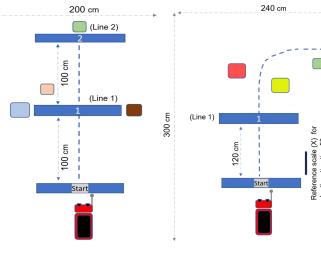
Experiment condition:
1) Location: Perception lab, RISE office, Kista.
2) Number of Trials (T): Eighteen randomized T.
3) Total time: 1 to 1.5 hours including breaks.

Pilot test

220 cm

Main test





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Questionnaires:

1) Background + Simulator Sickness Questionnaire (SSQ).

- 2) Recurring questionnaire consisting three sections.
- 3) Interview questionnaire + SSQ.

TEST CONFIGURATIONS WERE RANDOMLY APPLIED TO 18 TRIALS, THE COMBINATION OF LATENCY, FIELD OF VIEW, AND VIDEO QUALITY).

Trials	T1	T2	T3	T4	T5	T6	T7	T8	T9	T10	T11	T12	T13	T14	T15	T16	T17	T18
Quality levels	Q1	Q2	Q3	Q1	Q2	Q3	QI	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3
Latency levels	LI	LI	LI	L2	L2	L2	L3	L3	L3	LI	LI	LI	L2	L2	L2	L3	L3	L3
FoV levels	F1	F1	F1	F1	F1	F1	FI	F1	FI	F2								



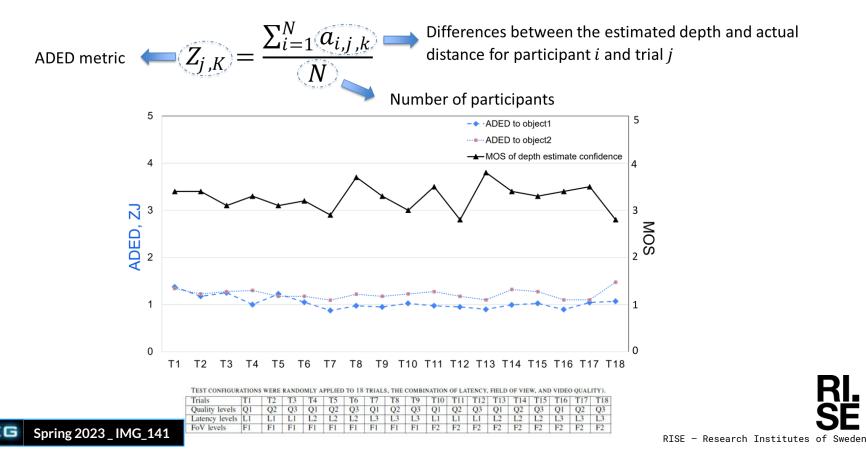


Results

Depth perception:

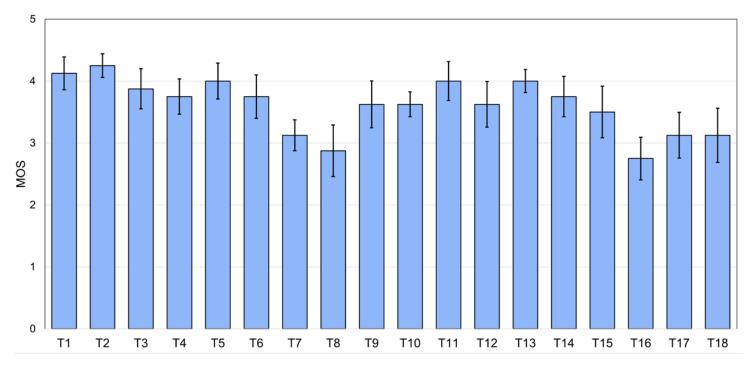
Depth perception-a: Average Depth Estimate Difference (ADED)

Depth perception-b: Users confidence rating (5-point Likert scale) to the estimated depth.



User experience:

Including user's comfort and overall UX (5-point Likert scale).



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Trials	TI	T2	T3	T4	T5	T6	T7	T8	T9	T10	T11	T12	T13	T14	T15	T16	T17	T18
Quality levels	Q1	Q2	Q3	Q1	Q2	Q3	QI	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3
Latency levels	LI	LI	LI	L2	L2	L2	L3	L3	L3	LI	LI	LI	L2	L2	L2	L3	L3	L3
FoV levels	F1	Fl	F1	F1	F1	F1	FI	F1	Fl	F2								



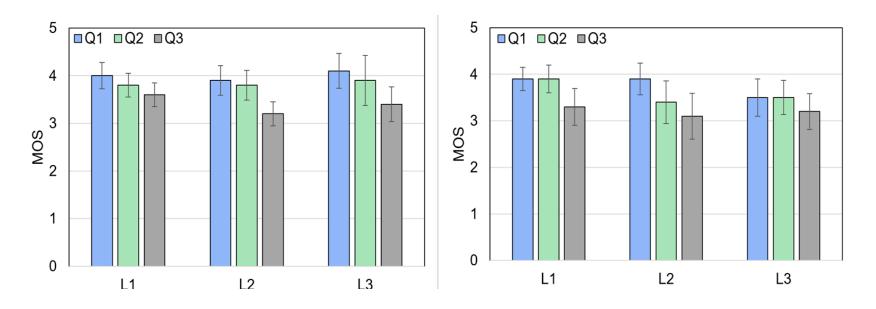
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User experience:

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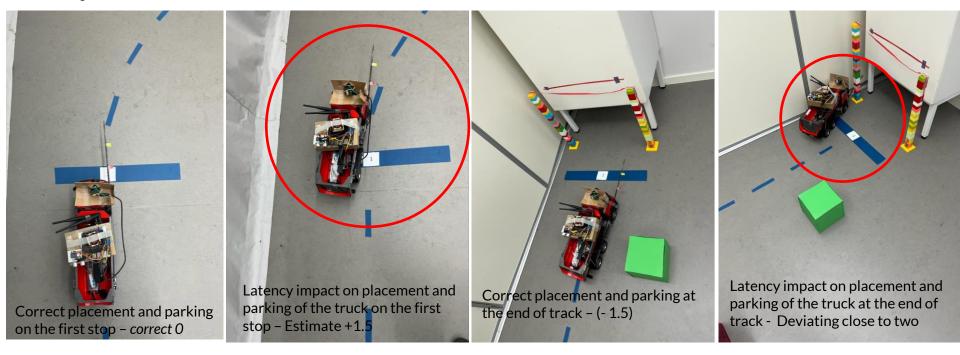
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Latency levels	LI	LI	LI	L2	L2	L2	L3	L3	L3	LI	LI	LI	L2	L2	L2	L3	L3	L3
FoV levels	F1	F1	F1	F1	F1	F1	FI	F1	Fl	F2								



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User performance error:



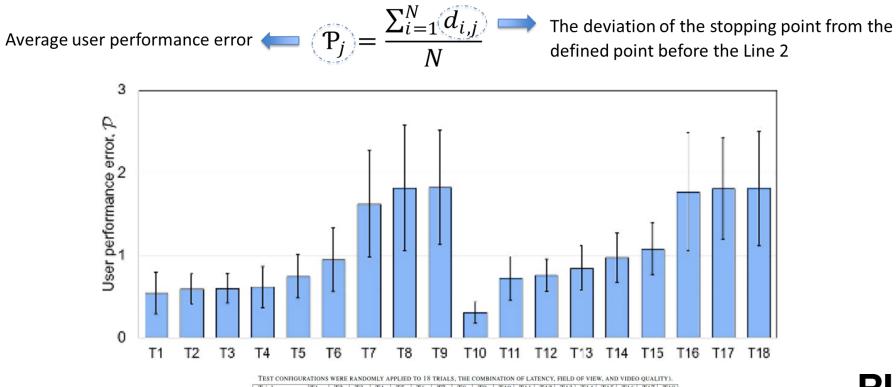
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Average user performance error $(P_j) = \frac{\sum_{i=1}^{N} (d_{i,j})}{N}$ The deviation of the stopping point from the defined point before the Line 2



User performance error:

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Trials	T1	T2	T3	T4	T5	T6	T7	T8	T9	T10	T11	T12	T13	T14	T15	T16	T17	T18
Quality levels	Q1	Q2	Q3	Q1	Q2	Q3	QI	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3	Q1	Q2	Q3
Latency levels	LI	LI	LI	L2	L2	L2	L3	L3	L3	LI	LI	LI	L2	L2	L2	L3	L3	L3
FoV levels	F1	Fl	F1	Fl	F1	F1	FI	F1	F1	F2								



Conclusion:

- The study meets ecological validity in the following ways:
 - The real-time video feed and remote interaction are similar to the real-world ToP systems.
 - The test setup, truck speed, and camera position are similar to the real-world ToP setup.
- Results shown:
 - A degradation in user performance, experience, and comfort with increased G2G latency.
 - The users' comfort improved with the increased video quality (i.e., spatial resolution).
 - Users' depth estimation and performance differed slightly for different fields of view.

Future study:

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• This study will extend to determine the entire QoE and UX to be adjusted as a user-centered design.



Thank you! Looking forward to your comments and feedback!

