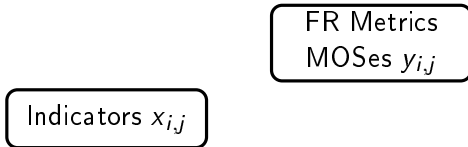


Data Analysis Proposition

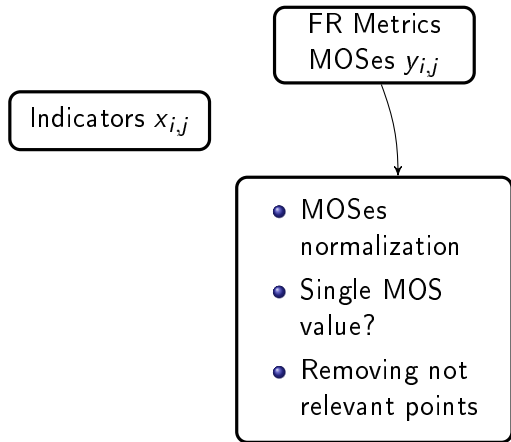
Lucjan Janowski, AGH

June 11, 2012

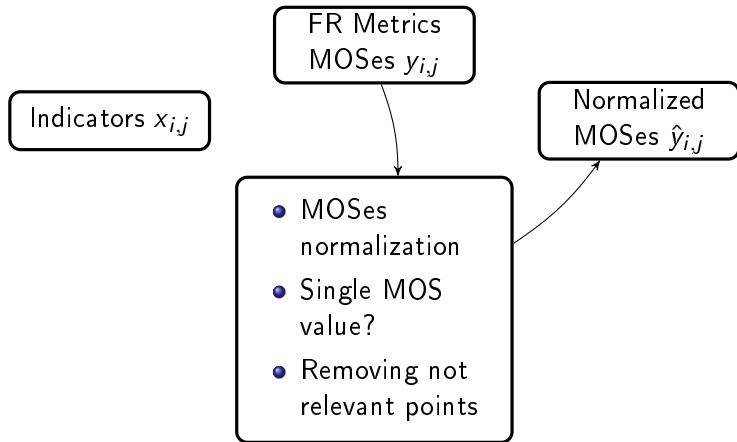
Data Flows



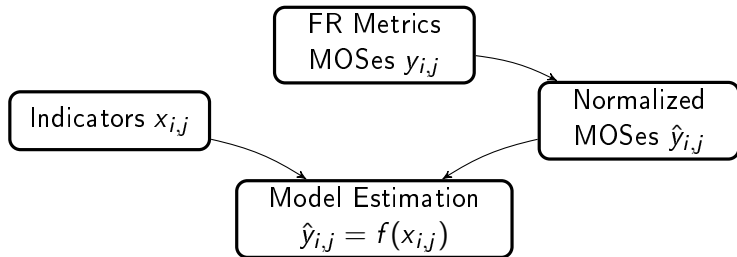
Data Flows



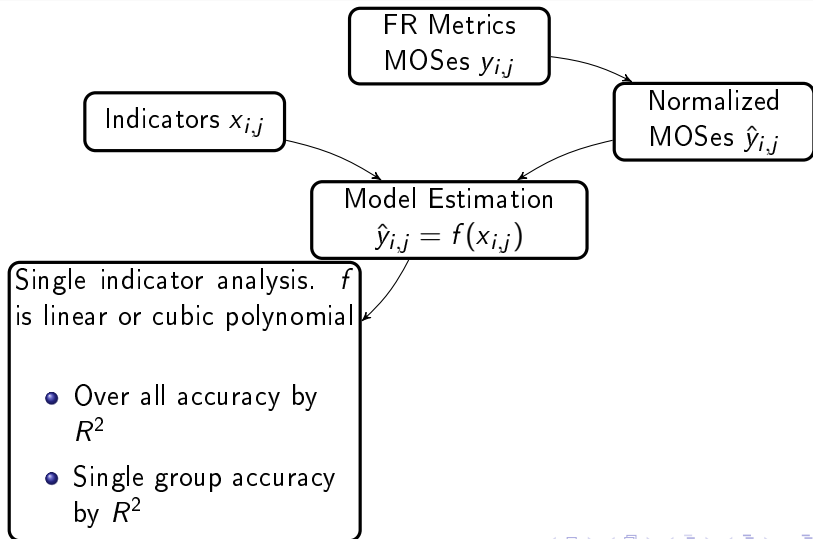
Data Flows



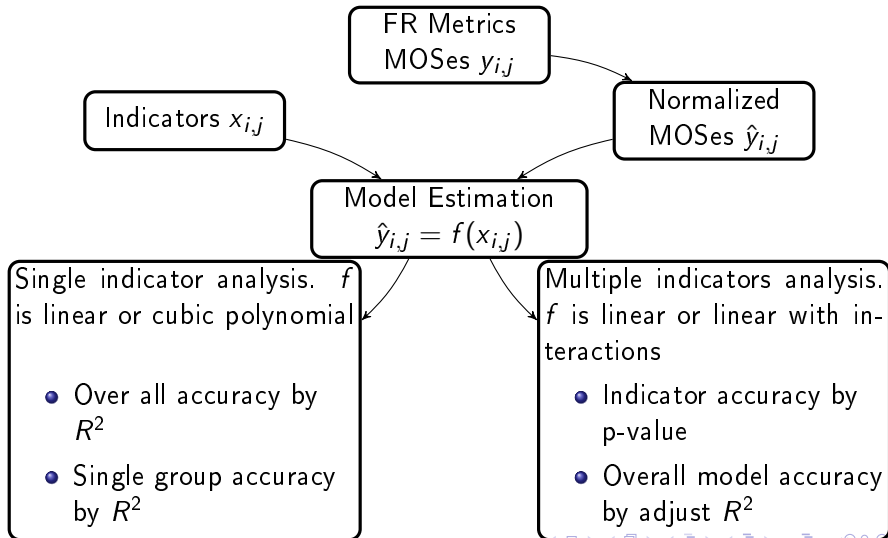
Data Flows



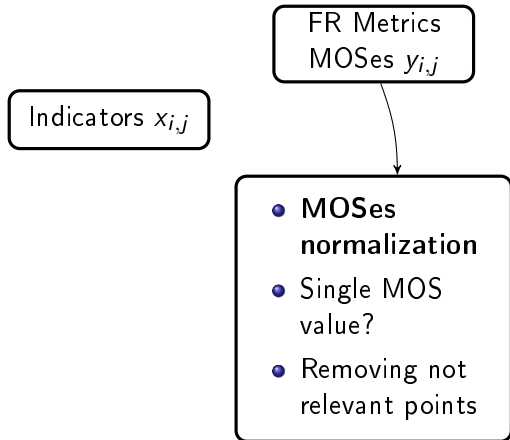
Data Flows



Data Flows



Data Flows



Normalization

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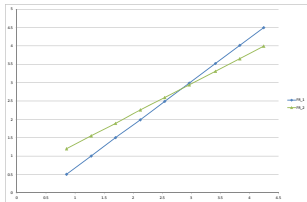
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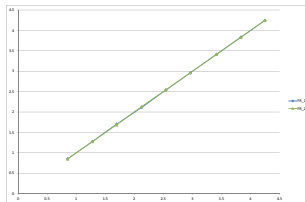
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- Mean MOS of all metrics works the best probably

Example

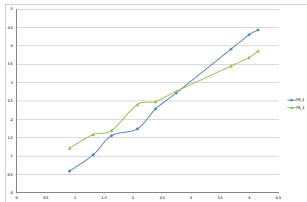


Input data

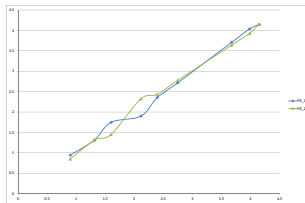


Normalized metrics

Example with Errors

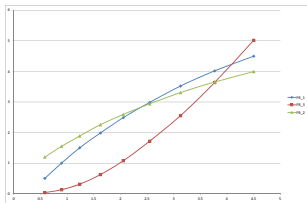


Input data

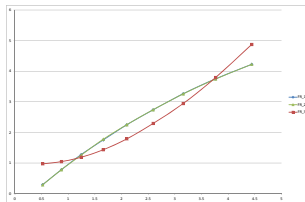


Normalized metrics

Example Non Linear

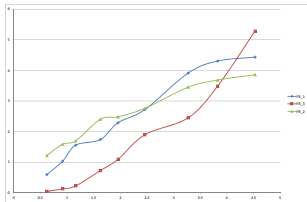


Input data

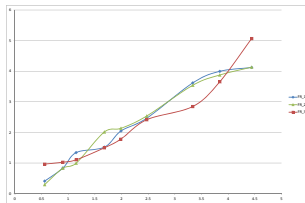


Normalized metrics

Example Non Linear with Errors

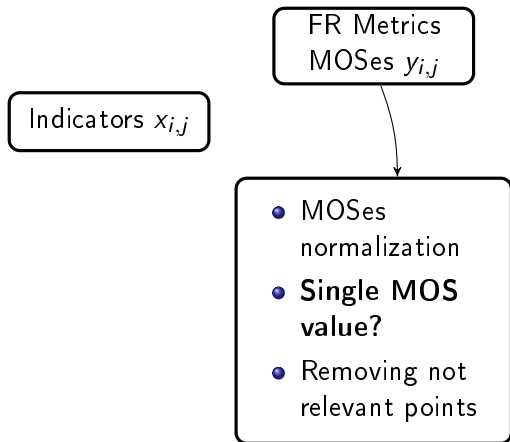


Input data



Normalized metrics

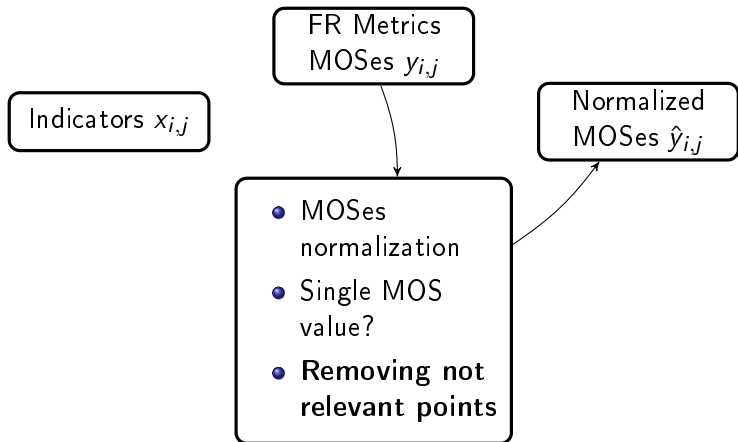
Data Flows



Single MOS or Multiple MOSes

- More points more information
- An alternative solution is regression including errors
- Is an error for 3-4 points really meaning full?
- If all points are used a perfect metric has R^2 different from 1 since the metrics inaccuracy makes the target function irrelevant

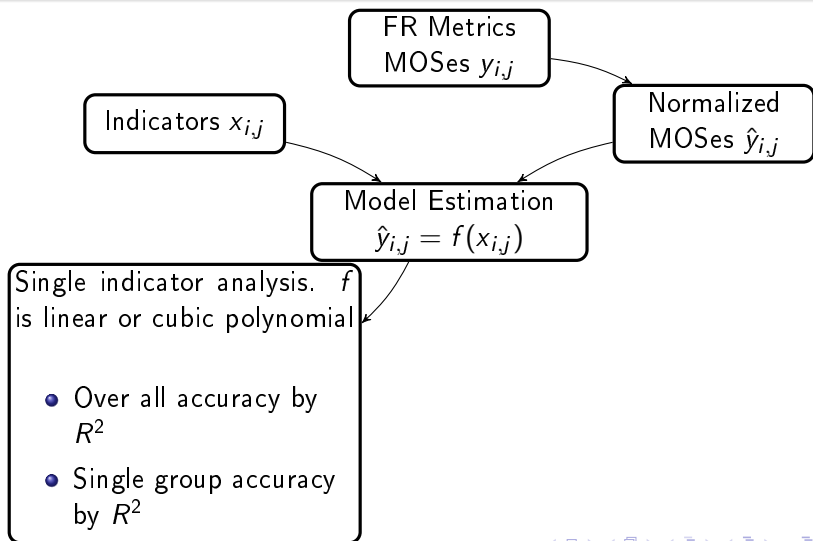
Data Flows



Removing not Relevant Points

- $|MOS_{i,1} - (aMOS_{i,2} + b)| > \epsilon$ is changed to $|\hat{y}_{i,1} - \hat{y}_{i,2}| > \epsilon$.
- For many metrics PVS_j is removed if $\max_j |\hat{y}_{i,j} - \hat{y}_{i,j}| > \epsilon$
- What should be ϵ value?
- Typical subjective experiment error? Which is?

Data Flows



PVS Grouping

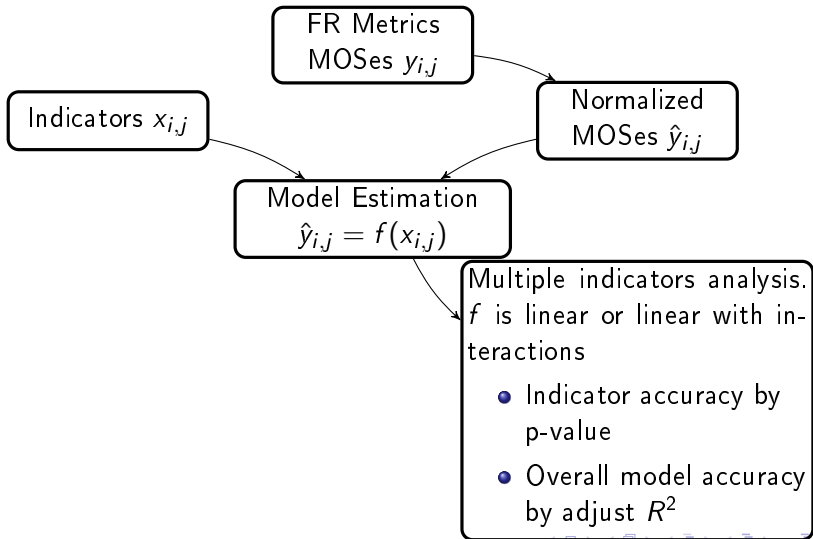
- An indicator can work just for some PVSeS (e.g. frame rate change only)
- Single PVS can be a member of many different groups
- Each analysis is performed on each group including all data
- Group of PVSeS is a set of i indexes I_k

Analysis

Let us consider metric number 1

- Estimate a and b of a linear fit $\hat{y}_{i,j} = ax_{i,1} + b$ for $i \in I_k$ and all j and k
- Calculate R^2 for the obtained fit
- $x_{i,1}$ normalization by $\frac{x_{i,1} - \bar{x}_1}{\sigma_{x_{i,1}}}$ where $\sigma_{x_{i,1}}$ is the standard deviation
- Estimate a cubic fit for $\hat{y}_{i,j} = \sum_{l=0}^3 a_l x_{i,1}^l$ for $i \in I_k$ and all j and k
- Chucking p-values of a_l - is the metric non linear?
- Calculate R^2 for the obtained fit

Data Flows



Analysis

- $x_{i,1}$ normalization by $\frac{x_{i,1} - \bar{x}_1}{\sigma_{x_{i,1}}}$ where $\sigma_{x_{i,1}}$ is standard deviation
- Estimate a linear fit $\hat{y}_{i,j} = \sum_l a_l x_{i,b_l} + b$ for $i \in I_k$ and all j, k and all possible combinations of b_l values - if possible
 $\hat{y}_{i,j} = a_1 x_{i,1} + a_2 x_{i,2} + b$; $\hat{y}_{i,j} = a_1 x_{i,1} + a_2 x_{i,3} + b$;
 $\hat{y}_{i,j} = a_1 x_{i,2} + a_2 x_{i,3} + b$; $\hat{y}_{i,j} = a_1 x_{i,1} + a_2 x_{i,2} + a_3 x_{i,3} + b$
- First step is p-values analysis: is particular indicator statistically important?
- Removing not statistically important indicators and than adjust R^2 computation

Analysis

- Metrics “cooperation” $\hat{y}_{i,j} = a_0 + a_1x_{i,1} + a_2x_{i,2} + a_3x_{i,1}x_{i,2}$ for $i \in I_k$ and all j and k
- First step is p-values analysis: is particular indicator statistically important? Looking especially on the metrics products coefficients
- Removing not statistically important indicators and than adjust R^2 computation